

NAME: \_\_\_\_\_

HW4

COLLABORATOR(S): \_\_\_\_\_

1. Consider the following x86 code for function **foo**:

```
(gdb) ds foo
Dump of assembler code for function foo:
0x0804846d <+0>:    push    ebp
0x0804846e <+1>:    mov     ebp,esp
0x08048470 <+3>:    sub     esp,0x28
0x08048473 <+6>:    lea    eax,[ebp-0x18]
0x08048476 <+9>:    mov     DWORD PTR [esp+0x4],eax
0x0804847a <+13>:   mov     DWORD PTR [esp],0x8048540
0x08048481 <+20>:   call   0x8048360 <scanf@plt>
0x08048486 <+25>:   lea    eax,[ebp-0x18]
0x08048489 <+28>:   mov     DWORD PTR [esp+0x4],eax
0x0804848d <+32>:   mov     DWORD PTR [esp],0x8048540
0x08048494 <+39>:   call   0x8048330 <printf@plt>
0x08048499 <+44>:   leave
0x0804849a <+45>:   ret
End of assembler dump.
(gdb) x/s 0x8048540
0x8048540: "%s"
```

5/3/1/0 a) **CIRCLE** the function call in the x86 code where there is a potential buffer overflow and security violation.

10/8/5/0 b) Write the equivalent C code for **foo** below.

10/8/5/0 c) Consider executing the program like so:

```
python -c "print 'A'*x" | ./main
```

What is the *smallest* value of **x** that will crash the program. **Explain** how this causes a crash. (*hint: you do not have to overflow to the return address to cause the first crash*)

2. Consider the following x86 code analysis for function **foo**:

(gdb) ds foo

Dump of assembler code for function foo:

```

0x0804844d <+0>:    push    ebp
0x0804844e <+1>:    mov     ebp,esp
0x08048450 <+3>:    sub     esp,0x48
0x08048453 <+6>:    mov     DWORD PTR [ebp-0xc],0x0
0x0804845a <+13>:   mov     eax,DWORD PTR [ebp+0x8]
0x0804845d <+16>:   mov     DWORD PTR [esp+0x4],eax
0x08048461 <+20>:   lea    eax,[ebp-0x2c]
0x08048464 <+23>:   mov     DWORD PTR [esp],eax
0x08048467 <+26>:   call   0x8048320 <strcpy@plt>
0x0804846c <+31>:   jmp    0x804848c <foo+63>
0x0804846e <+33>:   lea    eax,[ebp-0x2c]
0x08048471 <+36>:   mov     DWORD PTR [esp+0x8],eax
0x08048475 <+40>:   mov     eax,DWORD PTR [ebp-0xc]
0x08048478 <+43>:   mov     DWORD PTR [esp+0x4],eax
0x0804847c <+47>:   mov     DWORD PTR [esp],0x8048540
0x08048483 <+54>:   call   0x8048310 <printf@plt>
0x08048488 <+59>:   add     DWORD PTR [ebp-0xc],0x1
0x0804848c <+63>:   cmp     DWORD PTR [ebp-0xc],0x2
0x08048490 <+67>:   jle    0x804846e <foo+33>
0x08048492 <+69>:   leave
0x08048493 <+70>:   ret

```

End of assembler dump.

(gdb) r "Go Navy"

Starting program: /home/user/git/si485-binary-exploits/hw/04/demo/main "Go Navy"

0: Go Navy

1: Go Navy

2: Go Navy

10/8/5/0

[Inferior 1 (process 3044) exited with code 013]

a) Write the source code for the function **foo**:

b) Consider executing the program **main** which calls **foo** using the command line arguments like in the gdb code.

```
./main `python -c "print 'A'*x"`
```

At what value of **x** does the functionality of the loop change? **Explain.**

5/3/1/0

c) Complete a command line argument so that the loop will execute **4 times** and **Explain why.** (hint: 2's-compliment numbers)

10/8/5/0

```
./main `python -c "`
```

"`

3. Consider the disassembled x86 code below:

```
(gdb) ds foo
Dump of assembler code for function foo:
0x08048461 <+0>:    push    ebp
0x08048462 <+1>:    mov     ebp,esp
0x08048464 <+3>:    sub     esp,0x28
0x08048467 <+6>:    mov     eax,DWORD PTR [ebp+0x8]
0x0804846a <+9>:    mov     DWORD PTR [esp+0x4],eax
0x0804846e <+13>:   lea    eax,[ebp-0xc]
0x08048471 <+16>:   mov     DWORD PTR [esp],eax
0x08048474 <+19>:   call   0x8048310 <strcpy@plt>
0x08048479 <+24>:   lea    eax,[ebp-0xc]
0x0804847c <+27>:   mov     DWORD PTR [esp],eax
0x0804847f <+30>:   call   0x8048320 <puts@plt>
0x08048484 <+35>:   leave
0x08048485 <+36>:   ret
```

End of assembler dump.

```
(gdb) ds bar
Dump of assembler code for function bar:
0x0804844d <+0>:    push    ebp
0x0804844e <+1>:    mov     ebp,esp
0x08048450 <+3>:    sub     esp,0x18
0x08048453 <+6>:    mov     DWORD PTR [esp],0x8048540
0x0804845a <+13>:   call   0x8048320 <puts@plt>
0x0804845f <+18>:   leave
0x08048460 <+19>:   ret
```

End of assembler dump.

```
(gdb) x/s 0x8048540
0x8048540: "Beat Army!"
(gdb) r "Go Navy!"
Starting program: /home/user/git/si485-binary-exploits/hw/04/demo/main
"Go Navy!"
Go Navy!
[Inferior 1 (process 3129) exited with code 011]
```

a) Write the source code for **foo** and **bar**: 5/3/1/0

b) At what value of **x** will the **return address** be overwritten? **Explain**.

```
./main `python -c "print 'A'*x`
```

10/8/5/0

c) Complete the command line so that **bar** executed due to smashing the stack.

```
10/8/5/0 ./main `python -c " _____ "`
```

5/3/1/0

4. What is *shell code*? And what three properties must it have?

5. Match the **execve** arguments to their register settings for the system call:

(a) eax (b) ebx (c) ecx (d) edx

```
char * argv[] = {"/bin/sh", NULL};
execve(argv[0], argv, NULL);
```

5/3/1/0

6. Why does system calls use registers for passing arguments?

5/3/1/0

7. What registers is used for the return value? Why does this well match the system call return value semantics?

6. Consider the following x86 code that is initializing the arguments for the **exec** system call before the interrupt.

```
0x0804806e <+14>:    mov     eax,0xb
0x08048073 <+19>:    lea    ebx,[esp+0xc]
0x08048077 <+23>:    mov     ecx,DWORD PTR [esp]
0x0804807a <+26>:    mov     edx,0x0
0x0804807f <+31>:    int    0x80
```

Complete the stack diagram such that the shell code completes properly. The value of esp is 0xbffff72c.

10/8/5/0

